Servo test for robot arm in arduino IDE

Test for the correct robot arms angles with servo.  
In this test **Forward** is when arm is looking **AWAY** from the arduino uno board.

THESE TESTS DO NOT TAKE IN CONSIDERATION THE RELATION OF SEVERAL SERVOS ANGLES  
USED TOGETHER, ONLY **ONE SERVO PER USE.**

**BASE SWEEPER SERVO:**Middle point(looking forward) value: 75  
Right sweep max value: 00  
Left sweep max value: 150

**LEFT SIDE SERVO:**Middle point(looking forward) value: 110  
Forward reach max value: 60  
Backwards reach max value: 160

**RIGHT SIDE SERVO:**Middle point(looking forward) value: 100  
Forward reach max value: 170  
Backwards reach max value: 30 (watch out for LEFT side servos angle here…)

**CLAW SERVO:**Middle point(looking forward) value: 135  
Fully gripped value: 120 (gripped value can be 125 (ie more open) but for harder grip we chose 120)  
Fully open value: 150